

# **T0240** Draper Multi-Environment Navigation (DMEN) Suborbital DRAPER **Rocket Campaign**

#### **Technology Need**

EDL technology is vital to NASA's strategic plans. From NASA TA9: "... NASA cannot continue to rely on the EDL technology investments of the 1960's and 1970's as a baseline to enable future missions. NASA must develop new and innovative technologies to solve this problem ... " As exploration reaches further into the solar system both human missions and a multitude of smaller craft will perform will need to perform EDL to complete their missions. A small, reliable navigation package, such as Draper's, is a necessary technology.

#### **Technology Concept**

DMEN consists of a suite of sensors (camera, IMU, and magnetometer), with sensor circuitry, a computer, and a powerful suite of algorithms to process the sensor data into a navigation solution. The algorithms include Tracker (tightly coupled visual-inertial odometry), and IBAL (visual terrainbased absolute positioning). TRL for EDL applications is 4-5.

## **Technology Development Team**

PI: Dr. Brett Streetman, Principal Member Tech. Staff, Charles Stark Draper Laboratory, Inc. Co-Is: Courtney Mario, Dr. Ted Steiner, Draper

#### **Test Apparatus**

The Draper Multi-Environment Navigator (DMEN) is designed for simple integration and operation. It is a self-contained package that begins recording at power on. It weighs ~4lbs and fits within a volume of 12inx12inx8in. All necessary hardware is contained within the system (including IMU sensor, camera body, processing, sensor circuitry, and battery power), except for the external camera lens.

## **Flight Requirements/Objectives**

Flight plan overview: Two suborbital rocket flights, to be provided by Blue Origin on the New Sheppard vehicle. Each flight is to be to an altitude of >60km.

Flight 1. Objective: collect in-environment data with DMEN from high altitude. Personnel reg'd.: 2 Flight 2. Objective: collect data from altitude while running navigation algorithms. Personnel reg'd.: 2 Flight 1 Readiness Date: 03/01/2020

# DMEN Image from 1<sup>st</sup> Balloon Campaign

# **Technology Advancement**

The Draper package has achieved high TRL (6-7) for both ground and low altitude operations, but for the Descent portion of EDL is held at TRL 4 until it can be tested in a relevant environment. Suborbital flights will allow for the collection of data and validation of algorithms in this environment, advancing the system to TRL 5.

**Technology End Users** DMEN is designed to operate as a low SWAP navigation sensor for EDL. It can be used on human or robotic missions with a landing component as well as in orbit near small bodies. Algorithms are planned for use in Draper-led CLPS missions.

## Lunar/Planetary Descent & Landing Navigation